# LOCAL HIGHER INTEGRABILITY OF THE GRADIENT OF A QUASIMINIMIZER UNDER GENERALIZED ORLICZ GROWTH CONDITIONS 

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#### Abstract

We study local quasiminimizers of the Dirichlet energy under generalized growth conditions. Special cases include standard, variable exponent and double phase growths. We show that the gradient of a local quasiminimizer has local higher integrability.


## 1. Introduction

In this paper we study local quasiminimizers of the minimazation problem

$$
\min _{u \in W^{1,1}} \int_{\Omega} \varphi(x,|\nabla u|) d x .
$$

Here $\varphi$ satisfies generalized Orlicz type conditions, see Section 2. Our result covers, for example, $p(\cdot)$-type growth $\varphi(x, t)=t^{p(x)}$ and its perturbations $\varphi(x, t)=t^{p(x)} \log (e+t)$ $[6,7,18,27,30]$, and double phase growth $\varphi(x, t)=t^{p}+a(x) t^{q}[1,3,8,10,11]$. Other properties in the general case have been studied e.g. in [14, 21, 25, 28, 29]. More examples can be found from Section 2.

Our main result is the following.
Theorem 1.1 (Local higher integrability of the gradient). Let $\varphi \in \Phi_{w}\left(\mathbb{R}^{n}\right)$ satisfy assumptions (AO), (A1), (aInc) and (aDec) $)^{\infty}$. Let $\Omega \subset \mathbb{R}^{n}$ be a bounded domain and suppose $u \in W_{\mathrm{loc}}^{1, \varphi}(\Omega)$ is a local quasiminimzer of the $\varphi$-energy. Then there exists $\varepsilon>0$ such that

$$
\varphi(\cdot,|\nabla u|) \in L_{\mathrm{loc}}^{1+\varepsilon}(\Omega) .
$$

The idea of the proof is to combine a Sobolev-Poincaré inequality (Proposition 3.6), a Caccioppoli inequality (Lemma 4.2) and Gehring's lemma [17]. The hardest part is to prove a suitable modular type Sobolev-Poincaré inequality. Here we need to use equivalent more regular weak $\Phi$-functions.

In the variable exponent case, $\varphi(x, t)=t^{p(x)}$, higher integrability was proved by X.L. Fan and D. Zhao in [16]. They assumed that $1<\inf p \leqslant \sup p<\infty$ and $p$ is $\log$ Hölder continuous. These are special cases of our assumptions. In the double phase case, $\varphi(x, t)=t^{p}+a(x) t^{q}$ where $1<p<q$, Colombo and Mingione [9] proved the higher integrability of the gradient under assumption $\frac{q}{p}<1+\frac{\alpha}{n}$, where $\alpha$ is the Hölder exponent of the function $a$. Again, this is a special case of our assumption (A1). Our result also contains as special cases the perturbed variable exponent and the degenerate double phase cases (cf. (2.3)) where higher integrability was not previously know, as well as many other cases. Further information of our assumptions and related special cases are collected as a table in the next section.

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## 2. PROPERTIES OF GENERALIZED $\Phi$-FUNCTIONS

By $\Omega \subset \mathbb{R}^{n}$ we denote a bounded domain, i.e. an open and connected set. The notation $f \lesssim g$ means that there exists a constant $C>0$ such that $f \leqslant C g$. The notation $f \approx g$ means that $f \lesssim g \lesssim f$. By $c$ we denote a generic constant whose value may change between appearances. A function $f$ is almost increasing if there exists a constant $L \geqslant 1$ such that $f(s) \leqslant L f(t)$ for all $s \leqslant t$ (more precisely, $L$-almost increasing). Almost decreasing is defined analogously.

Definition 2.1. We say that $\varphi: \Omega \times[0, \infty) \rightarrow[0, \infty]$ is a weak $\Phi$-function, and write $\varphi \in \Phi_{w}(\Omega)$, if

- For every $t \in[0, \infty)$ the function $x \mapsto \varphi(x, t)$ is measurable and for every $x \in \Omega$ the function $t \mapsto \varphi(x, t)$ is increasing.
- $\varphi(x, 0)=\lim _{t \rightarrow 0^{+}} \varphi(x, t)=0$ and $\lim _{t \rightarrow \infty} \varphi(x, t)=\infty$ for every $x \in \Omega$.
- The function $t \mapsto \frac{\varphi(x, t)}{t}$ is $L$-almost increasing for $t>0$ for some $L \geqslant 1$ and every $x \in \Omega$.
- The function $t \mapsto \varphi(x, t)$ is left-continuous for $t>0$ and $x \in \Omega$.

We denote $\varphi \in \Phi_{c}(\Omega)$ and say that $\varphi$ is a convex $\Phi$-function if, additionally, $t \mapsto \varphi(x, t)$ is convex.

Two functions $\varphi$ and $\psi$ are equivalent, $\varphi \simeq \psi$, if there exists $L \geqslant 1$ such that $\psi\left(x, \frac{t}{L}\right) \leqslant$ $\varphi(x, t) \leqslant \psi(x, L t)$ for every $x \in \Omega$ and every $t>0$. Equivalent $\Phi$-functions give rise to the same space with comparable norms. By $\varphi^{-1}$ we denote the left-continuous inverse of a weak $\Phi$-function $\varphi$,

$$
\varphi^{-1}(x, \tau):=\inf \{t \geqslant 0: \varphi(x, t) \geqslant \tau\}
$$

We say that $\varphi$ is doubling if there exists a constant $L \geqslant 1$ such that $\varphi(x, 2 t) \leqslant L \varphi(x, t)$ for every $x \in \Omega$ and every $t \geqslant 0$. If $\varphi$ is doubling with constant $L$, then by iteration

$$
\begin{equation*}
\varphi(x, t) \leqslant L^{2}\left(\frac{t}{s}\right)^{Q} \varphi(x, s) \tag{2.2}
\end{equation*}
$$

for every $x \in \Omega$ and every $0<s<t$, where $Q=\log _{2}(L)$. For the proof see for example [5, Lemma 3.3, p. 66]. If $\varphi$ is doubling, then (2.2) shows that $\simeq$ implies $\approx$. On the other hand, $\approx$ always implies $\simeq$ since the function $t \mapsto \frac{\varphi(x, t)}{t}$ is almost increasing; hence $\simeq$ and $\approx$ are equivalent in the doubling case. Note that doubling also yields that $\varphi(x, t+s) \leqslant$ $L \varphi(x, t)+L \varphi(x, s)$.

Let us write $\varphi_{B}^{+}(t):=\sup _{x \in B} \varphi(x, t)$ and $\varphi_{B}^{-}(t):=\inf _{x \in B} \varphi(x, t) ;$ and abbreviate $\varphi^{ \pm}:=$ $\varphi_{\Omega}^{ \pm}$. Assume that there exists a constant $\sigma>0$ such that the following two conditions hold.
(A0) There exists $\beta \in(0,1)$ such that $\varphi^{+}(\beta \sigma) \leqslant 1 \leqslant \varphi^{-}(\sigma)$.
(A1) There exists $\beta \in(0,1)$ such that

$$
\varphi_{B}^{+}(\beta t) \leqslant \varphi_{B}^{-}(t)
$$

for every $t \in\left[\sigma,\left(\varphi_{B}^{-}\right)^{-1}\left(\frac{1}{|B|}\right)\right]$ and every ball B with $\left(\varphi_{B}^{-}\right)^{-1}\left(\frac{1}{|B|}\right) \geqslant \sigma$.
We also introduce the following assumptions, which are of different nature. They are related to the $\Delta_{2}$ and $\nabla_{2}$ conditions from Orlicz space theory.
(aInc) $)_{p}$ There exists $L \geqslant 1$ such that $t \mapsto \frac{\varphi(x, t)}{t^{p}}$ is $L$-almost increasing in $(0, \infty)$.
$(\mathrm{aDec})_{q}^{\infty}$ There exists $L \geqslant 1$ such that $t \mapsto \frac{\varphi(x, t)+1}{t^{q}}$ is $L$-almost decreasing in $(0, \infty)$.
We write (aInc) if there exists $p>1$ such that (aInc) ${ }_{p}$ holds, similarly for (aDec) ${ }^{\infty}$. Further, we write $(\mathrm{aDec})_{q}$ if $(\mathrm{aDec})_{q}^{\infty}$ has no " +1 " term. This is equivalent to doubling [25, Lemma 2.6]. These conditions are invariant under equivalence of $\Phi$-functions.

The condition $(\mathrm{aDec})_{q}^{\infty}$ is new to this paper, but it corresponds to doubling at infinity, $\Delta_{2}(\infty)$, which is the base form of doubling in Rao-Ren [31]. (What is here called doubling, they call globally doubling.) It can equivalently be written as the requirement that $t \mapsto \frac{\varphi(x, t)}{t^{q}}$ is $L$-almost decreasing for values $t>0$ such that $\varphi(x, t) \geqslant 1$. The constant 1 has been chosen for convenience and the choice does not play a significant role.

The reason for considering doubling at infinity rather than the full range is that some researchers [12,13] have recently considered the following variant of the double phase functional,

$$
\begin{equation*}
F(x, t) \approx(t-1)_{+}^{p}+a(x)(t-1)_{+}^{q}, \tag{2.3}
\end{equation*}
$$

with $(s)_{+}:=\max \{s, 0\}$, which is singular even for positive values of the gradient. Clearly, this is not doubling, but it does satisfy the condition $(\mathrm{aDec})_{q}^{\infty}$.

In results to come, positive constants, such as $c$, might depend on the weak $\Phi$-function $\varphi$. This means that they may depend on all or some of the following parameters: $\beta, \sigma, p$ and $q$. In such cases we denote for example $c=c(n, \varphi)$ if $c$ depends on the dimension $n$ and some of the parameters of $\varphi$.

The next table interprets the assumptions in the context of variable exponent and double phase growth.

| $\varphi(x, t)$ | $(\mathrm{A} 0)$ | $(\mathrm{A} 1)$ | $(\mathrm{aInc})$ | $(\mathrm{aDec})$ | $(\mathrm{aDec})^{\infty}$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| $t^{p(x)} a(x)$ | $a \approx 1$ | $p \in C^{\log }$ | $p^{-}>1$ | $p^{+}<\infty$ | $p^{+}<\infty$ |
| $t^{p}+a(x) t^{q}$ | $a \in L^{\infty}$ | $a \in C^{\frac{n}{p}(q-p)}$ | $p>1$ | $q<\infty$ | $q<\infty$ |
| $(t-1)_{+}^{p}+a(x)(t-1)_{+}^{q}$ | $a \in L^{\infty}$ | $a \in C^{\frac{n}{p}(q-p)}$ | $p>1$ | false | $q<\infty$ |

Remark 2.4. In the double phase case, the assumption $a \in C^{\frac{n}{p}(q-p)}$ or (A1) is related to the boundedness of the maximal operator and several other properties that can be obtained through it. These kind of properties are also used in this paper. However, Baroni-ColomboMingione [2, 3, 4] have shown that a weaker assumption suffices if one has additional information about the minimizer $u$. Namely, if $u$ is locally bounded then $a \in C^{q-p}$ suffices for higher integrability, whereas if $u \in C^{\gamma}$, then $a \in C^{(1-\gamma)(q-p)}$ suffices. With the method of this paper, it is not possible to use possible additional information about $u$ to recover these results, so this remains for future research.

Generalized Orlicz and Orlicz-Sobolev spaces have been studied with our assumptions in $[22,23,24,25]$. We recall some definitions. We denote by $L^{0}(\Omega)$ the set of measurable functions in $\Omega$ and the integral average of a function $f$ over a set $A$ is denoted by $f_{A} f(x) d x=: f_{A}$. Also, if $B$ is a ball with radius $r$, then $t B$ is a concentric ball with radius $t r$.

Definition 2.5. Let $\varphi \in \Phi_{w}(\Omega)$ and define the modular $\varrho_{\varphi}$ for $f \in L^{0}(\Omega)$ by

$$
\varrho_{\varphi}(f):=\int_{\Omega} \varphi(x,|f(x)|) d x .
$$

The generalized Orlicz space, also called Musielak-Orlicz space, is defined as the set

$$
L^{\varphi}(\Omega):=\left\{f \in L^{0}(\Omega): \lim _{\lambda \rightarrow 0^{+}} \varrho_{\varphi}(\lambda f)=0\right\}
$$

equipped with the (Luxemburg) norm

$$
\|f\|_{L^{\varphi}(\Omega)}:=\inf \left\{\lambda>0: \varrho_{\varphi}\left(\frac{f}{\lambda}\right) \leqslant 1\right\} .
$$

If the set is clear from the context we abbreviate $\|f\|_{L^{\varphi}(\Omega)}$ by $\|f\|_{\varphi}$.

A function $u \in L^{\varphi}(\Omega)$ belongs to the Orlicz-Sobolev space $W^{1, \varphi}(\Omega)$ if its weak partial derivatives $\partial_{1} u, \ldots, \partial_{n} u$ exist and belong to $L^{\varphi}(\Omega)$.

## 3. AUXILIARY RESULTS

We start with three lemmas regarding Jensen type inequalities for $\Phi_{w}(\Omega)$-functions. The first one concerns a $\Phi$-prefunction $\varphi$, which is a weak $\Phi$-function without the left-continuity. Note also that first we also consider $\varphi$ independent of $x$.

Lemma 3.1. Let $\varphi$ be a prefunction that satisfies (aInc) $)_{p}, p \geqslant 1$. Then there exists $\beta_{0}>0$ such that the following Jensen-type inequality holds for every $f \in L_{\mathrm{loc}}^{1}(\Omega)$ and every ball $B \subset \Omega$ :

$$
\varphi\left(\beta_{0} f_{B} f d x\right)^{\frac{1}{p}} \leqslant f_{B} \varphi(f)^{\frac{1}{p}} d x
$$

Proof. Since $\varphi^{1 / p}$ satisfies (aInc) $)_{1}$, there exists $\psi \in \Phi_{c}(\Omega)$ such that $\psi \simeq \varphi^{1 / p}$, by [24, Lemma 2.2]. By Jensen's inequality for $\psi$,

$$
\varphi\left(\frac{1}{L^{2}} f_{B} f d x\right)^{\frac{1}{p}} \leqslant \psi\left(f_{B} \frac{1}{L} f d x\right) \leqslant f_{B} \psi\left(\frac{1}{L} f\right) d x \leqslant f_{B} \varphi(f)^{\frac{1}{p}} d x .
$$

The proof of the next lemma is slightly modified version of Lemma 4.4 of [26]. The original was only stated for convex $\varphi$. For completeness, we present a proof of the slight generalization. Since we are interested in bounded domain $\Omega$, the assumption (A2) from the original proof can be omitted.
Lemma 3.2. Let $\varphi \in \Phi_{w}(B)$ satisfy assumptions (A0), (A1) and (aInc) ${ }_{p}, p \geqslant 1$. There exists $\beta_{1}=\beta_{1}(\varphi)>0$ such that

$$
\varphi\left(x, \beta_{1} f_{B}|f| d y\right)^{\frac{1}{p}} \leqslant f_{B} \varphi(y, f)^{\frac{1}{p}} d y+1
$$

for every ball $B$ and $f \in L^{\varphi}(B)$ with $\varrho_{\varphi}\left(f \chi_{\{|f|>\sigma\}}\right)<1$, where $\sigma$ is the constant in $(A 0)$ and (Al).

Proof. We may assume without loss of generality that $f \geqslant 0$. Fix a ball $B$ and $x \in B$. Denote $f_{1}:=f \chi_{\{f>\sigma\}}, f_{2}:=f-f_{1}$, and $A_{i}:=f_{B} f_{i} d y$. Since $\varphi^{1 / p}$ is increasing,

$$
\varphi\left(x, \beta_{1} f_{B} f d y\right)^{\frac{1}{p}} \leqslant \varphi\left(x, 2 \beta_{1} \max \left\{A_{1}, A_{2}\right\}\right)^{\frac{1}{p}} \leqslant \varphi\left(x, 2 \beta_{1} A_{1}\right)^{\frac{1}{p}}+\varphi\left(x, 2 \beta_{1} A_{2}\right)^{\frac{1}{p}}
$$

Since $\varphi$ satisfies (A0), a short calculation gives that $\varphi_{B}^{-}$satisfies the conditions of Lemma 3.1 with $p=1$. Thus Lemma 3.1 and $\varrho_{\varphi}\left(f \chi_{\{|f|>\sigma\}}\right)<1$ yield that

$$
\begin{equation*}
\varphi_{B}^{-}\left(\beta_{0} A_{1}\right) \leqslant f_{B} \varphi_{B}^{-}\left(f_{1}\right) d y \leqslant f_{B} \varphi\left(y, f_{1}\right) d y<\frac{1}{|B|} . \tag{3.3}
\end{equation*}
$$

Suppose first that $\beta_{0} A_{1} \geqslant \sigma$. This assumption and (3.3) yield that $\beta_{0} A_{1}$ is in the allowed range of (A1). Thus

$$
\varphi\left(x, \beta \beta_{0} A_{1}\right)^{\frac{1}{p}} \leqslant \varphi_{B}^{-}\left(\beta_{0} A_{1}\right)^{\frac{1}{p}} \leqslant f_{B} \varphi_{B}^{-}\left(f_{1}\right)^{\frac{1}{p}} d y \leqslant f_{B} \varphi\left(y, f_{1}\right)^{\frac{1}{p}} d y .
$$

Next consider $\beta_{0} A_{1} \leqslant \sigma$. Using (aInc) ${ }_{p}$ and (A0), we conclude that

$$
\begin{equation*}
\varphi\left(x, \beta^{2} \beta_{0} A_{1}\right)^{\frac{1}{p}} \leqslant \varphi(x, \beta \sigma)^{\frac{1}{p}} \frac{L \beta \beta_{0}}{\sigma} A_{1} \leqslant c f_{B} \frac{f_{1}}{\sigma} d y \tag{3.4}
\end{equation*}
$$

By $(\mathrm{A} 0), 1 \leqslant \varphi(y, \sigma)$. If $f_{1}>\sigma$, it follows from $(\mathrm{aInc})_{p}$ and $(\mathrm{A} 0)$ that

$$
\frac{f_{1}}{\sigma} \leqslant L \frac{\varphi\left(y, f_{1}\right)^{\frac{1}{p}}}{\varphi(y, \sigma)^{\frac{1}{p}}} \leqslant L \varphi\left(y, f_{1}\right)^{\frac{1}{p}}
$$

The inequality is trivial when $f_{1}(x)=0$, and by definition $f_{1}$ does not take values in $(0, \sigma)$. Thus the inequality holds in all cases. From (3.4) we then deduce

$$
\varphi\left(x, \beta^{2} \beta_{0} A_{1}\right)^{\frac{1}{p}} \leqslant c f_{B} \varphi\left(y, f_{1}\right)^{\frac{1}{p}} d y
$$

In view of this and the conclusion of previous paragraph, we find that

$$
\varphi\left(x, \frac{1}{L c} \beta^{2} \beta_{0} A_{1}\right)^{\frac{1}{p}} \leqslant \frac{1}{c} \varphi\left(x, \beta^{2} \beta_{0} A_{1}\right)^{\frac{1}{p}} \leqslant f_{B} \varphi\left(y, f_{1}\right)^{\frac{1}{p}} d y \leqslant f_{B} \varphi(y, f)^{\frac{1}{p}} d y
$$

where we also used (aInc) ${ }_{p}$ for the first inequality.
For $f_{2}$, we note that $A_{2} \leqslant \sigma$, since $f_{2} \leqslant \sigma$. Thus it follows from (A0) that

$$
\varphi\left(x, \beta A_{2}\right) \leqslant \varphi(x, \beta \sigma) \leqslant 1
$$

Adding the estimates for $f_{1}$ and $f_{2}$, we obtain the claim with constant $\beta_{1}=\min \left\{\frac{\beta}{2}, \frac{\beta^{2} \beta_{0}}{2 L c}\right\}$.

Lemma 3.5. Let $\varphi \in \Phi_{w}(B)$ satisfy assumptions $(A O)$, (Al) and (aInc) ${ }_{p}, p \geqslant 1$. Then there exists $\beta_{2}=\beta_{2}(n, \varphi)>0$ such that

$$
\varphi\left(x, \beta_{2} \int_{B} \frac{|f(y)|}{\operatorname{diam} B|x-y|^{n-1}} d y\right)^{\frac{1}{s}} \leqslant \int_{B} \frac{\varphi(y,|f(y)|)^{\frac{1}{s}}}{\operatorname{diam} B|x-y|^{n-1}} d y+1
$$

for almost every $x$ in the ball $B, 1 \leqslant s \leqslant p$ and every $f \in L^{\varphi}(B)$ with $\varrho_{\varphi}\left(f \chi_{\{|f|>\sigma\}}\right)<1$.
Proof. We may assume without loss of generality that $f \geqslant 0$. Fix $r>0$ and let $B$ be a ball with radius $r$. Define annuli $A_{k}:=\left\{y \in B: 2^{-k} r \leqslant|x-y| \leqslant 2^{1-k} r\right\}$ for $k \geqslant 1$. We split $B$ into annuli $A_{k}$ and obtain

$$
\int_{B} \frac{f(y)}{2 r|x-y|^{n-1}} d y \leqslant c_{1} \sum_{k=1}^{\infty} 2^{-k} f_{B\left(x, 2^{1-k} r\right)} \chi_{A_{k}} f(y) d y
$$

By [26, Lemma 3.2] there exists a $\Phi$-function $\psi$ such that $\varphi \simeq \psi$ and $\psi^{1 / p}$ is convex. Fix $s \in[1, p]$. Since $\sum_{k=1}^{\infty} 2^{-k}=1$, it follows by convexity of $\psi^{1 / s}$ that

$$
\begin{aligned}
\varphi\left(x, \frac{1}{L^{2}} \sum_{k=1}^{j} 2^{-k} f_{B\left(x, 2^{1-k} r\right)} \chi_{A_{k}} f(y) d y\right)^{\frac{1}{s}} & \leqslant \psi\left(x, \frac{1}{L} \sum_{k=1}^{j} 2^{-k} f_{B\left(x, 2^{1-k} r\right)} \chi_{A_{k}} f(y) d y\right)^{\frac{1}{s}} \\
& \leqslant \sum_{k=1}^{j} 2^{-k} \psi\left(x, \frac{1}{L} f_{B\left(x, 2^{1-k} r\right)} \chi_{A_{k}} f(y) d y\right)^{\frac{1}{s}} \\
& \leqslant \sum_{k=1}^{\infty} 2^{-k} \varphi\left(x, f_{B\left(x, 2^{1-k} r\right)} \chi_{A_{k}} f(y) d y\right)^{\frac{1}{s}}
\end{aligned}
$$

and by left continuity of $\varphi$

$$
\varphi\left(x, \frac{1}{L^{2}} \sum_{k=1}^{\infty} 2^{-k} f_{B\left(x, 2^{1-k} r\right)} \chi_{A_{k}} f(y) d y\right)^{\frac{1}{s}} \leqslant \sum_{k=1}^{\infty} 2^{-k} \varphi\left(x, f_{B\left(x, 2^{1-k} r\right)} \chi_{A_{k}} f(y) d y\right)^{\frac{1}{s}}
$$

Let $\beta_{1}>0$ be from Lemma 3.2. We obtain

$$
(I):=\varphi\left(x, \frac{\beta_{1}}{L^{2} c_{1}} \int_{B} \frac{f(y)}{r|x-y|^{n-1}} d y\right)^{\frac{1}{s}} \leqslant \sum_{k=1}^{\infty} 2^{-k} \varphi\left(x, \beta_{1} f_{B\left(x, 2^{1-k} r\right)} \chi_{A_{k}} f(y) d y\right)^{\frac{1}{s}}
$$

so Lemma 3.2 yields

$$
\begin{aligned}
(I) & \leqslant \sum_{k=1}^{\infty} 2^{-k}\left(f_{B\left(x, 2^{1-k} r\right)} \chi_{A_{k}} \varphi(y, f(y))^{\frac{1}{s}} d y+1\right) \\
& \leqslant \frac{1}{2} \sum_{k=1}^{\infty} \frac{2^{1-k}}{\left|B\left(x, 2^{1-k} r\right)\right|} \int_{B\left(x, 2^{1-k} r\right)} \chi_{A_{k}} \varphi(x, f(y))^{\frac{1}{s}} d y+1 \\
& \leqslant \sum_{k=1}^{\infty} \frac{1}{2 r\left(2^{1-k} r\right)^{n-1}} \int_{B\left(x, 2^{1-k} r\right)} \chi_{A_{k}} \varphi(y, f(y))^{\frac{1}{s}} d y+1 \leqslant \int_{B} \frac{\varphi(y, f(y))^{\frac{1}{s}}}{2 r|x-y|^{n-1}} d y+1 .
\end{aligned}
$$

This is the claim for $\beta_{2}=\frac{\beta_{1}}{L^{2} c_{1}}$.
The next proposition is a Sobolev-Poincaré inequality for weak $\Phi$-functions and yields an exponent strictly less than 1 . This is the main requirement for Gehring's lemma later on. The proof introduces a probability measure that allows Jensen's inequality to be used in the usual setting. This technique was used in [15]. The rest of the proof consists of handling leftover terms and technicalities.

Proposition 3.6. Let $\varphi \in \Phi_{w}(B)$ satisfy assumptions (A0), (A1) and (aInc) ${ }_{p}, p \geqslant 1$, and let $s \in[1, p]$ with $s<\frac{n}{n-1}$. Then there exists a constant $\beta_{3}=\beta_{3}(n, s, \varphi)$ such that

$$
f_{B} \varphi\left(x, \beta_{3} \frac{\left|u-u_{B}\right|}{\operatorname{diam} B}\right) d x \leqslant\left(f_{B} \varphi(x,|\nabla u|)^{\frac{1}{s}} d x\right)^{s}+1
$$

for every $v \in W^{1,1}(B)$ with $\|\nabla u\|_{\varphi}<1$.
Proof. For brevity, we denote $\kappa:=\operatorname{diam} B$. Suppose first that $\varphi(x,|\nabla u|)=0$ for almost every $x \in B$. Then by (A0) we see that $|\nabla u(x)| \leqslant \sigma$ that is $|\nabla u| \in L^{\infty}(B)$ and thus $u$ is Lipschitz continuous. Hence

$$
\left|u(x)-u_{B}\right|=|u(x)-u(y)| \leqslant \sigma \kappa
$$

for some $y \in B$ and

$$
f_{B} \varphi\left(x, \beta \frac{\left|u-u_{B}\right|}{\kappa}\right) d x \leqslant f_{B} \varphi(x, \beta \sigma) d x \leqslant 1 .
$$

Thus the proposition is true if the integral on the right-hand side is 0 .
Assume then that the integral on the right-hand side of inequality in the claim is positive. We have for almost every $x \in B$, by [19, Chapter 7],

$$
\left|u(x)-u_{B}\right| \leqslant C_{1}(n) \int_{B} \frac{|\nabla u(y)|}{|x-y|^{n-1}} d y .
$$

The previous inequality and Lemma 3.5 with constant $\beta^{\prime}=\frac{2 \beta_{2}}{C_{1}}$ yield

$$
\begin{align*}
\varphi\left(x, \beta^{\prime} \frac{\left|u(x)-u_{B}\right|}{\kappa}\right) & \leqslant \varphi\left(x, \beta_{2} \int_{B} \frac{|\nabla u(y)|}{\kappa|x-y|^{n-1}} d y\right) \\
& \leqslant\left(\int_{B} \frac{\varphi(y,|\nabla u(y)|)^{\frac{1}{s}}}{\kappa|x-y|^{n-1}} d y+1\right)^{s}  \tag{3.7}\\
& \leqslant 2^{s-1}\left(\int_{B} \frac{\varphi(y,|\nabla u(y)|)^{\frac{1}{s}}}{\kappa|x-y|^{n-1}} d y\right)^{s}+2^{s-1}
\end{align*}
$$

Set $J:=\int_{B} \varphi(x,|\nabla u|)^{1 / s} d x>0$ and define a measure by $d \mu(y):=\frac{1}{J} \varphi(y,|\nabla u|)^{1 / s} d y$. Then

$$
\int_{B} \frac{\varphi(y,|\nabla u(y)|)^{\frac{1}{s}}}{\kappa|x-y|^{n-1}} d y=\int_{B} \frac{J}{\kappa|x-y|^{n-1}} d \mu(y) .
$$

Since $\mu$ is a probability measure, we can use Jensen's inequality for the convex function $t \mapsto t^{s}$ :

$$
\left(\int_{B} \frac{\varphi(y,|\nabla u(y)|)^{\frac{1}{s}}}{\kappa|x-y|^{n-1}} d y\right)^{s} \leqslant \int_{B} \frac{J^{s}}{\kappa^{s}|x-y|^{s(n-1)}} d \mu(y)=J^{s-1} \int_{B} \frac{\varphi(y,|\nabla u|)^{1 / s}}{\kappa^{s}|x-y|^{s(n-1)}} d y
$$

We integrate the previous inequality over $x \in B$, and use Fubini's theorem to change the order of integration

$$
f_{B}\left(\int_{B} \frac{\varphi(y,|\nabla u(y)|)^{\frac{1}{s}}}{\kappa|x-y|^{n-1}} d y\right)^{s} d x=J^{s-1} f_{B} \varphi(y,|\nabla u(y)|)^{\frac{1}{s}} \int_{B} \frac{d x}{\kappa^{s}|x-y|^{s(n-1)}} d y
$$

Finally, we use the assumption $s<\frac{n}{n-1}$ to estimate

$$
\int_{B} \frac{d x}{\kappa^{s}|x-y|^{s(n-1)}} \leqslant c \kappa^{-s(n-1)+n-s}=c \kappa^{n-s n}
$$

for $y \in B$ and conclude, taking into account the definition of $J$, that

$$
f_{B}\left(\int_{B} \frac{\varphi(y,|\nabla u(y)|)^{\frac{1}{s}}}{\kappa|x-y|^{n-1}} d y\right)^{s} d x \leqslant c\left(\frac{J}{\kappa^{n}}\right)^{s}=c\left(f_{B} \varphi(y,|\nabla u(y)|)^{\frac{1}{s}} d y\right)^{s}
$$

Combining this with (3.7), which is integrated over $B$, we complete the proof as the constant $c$ can be absorbed into $\beta^{\prime}$ by $(\mathrm{aInc})_{1}$.

## 4. Higher integrability

Next we turn to properties of the minimizing function $u$, namely the Caccioppoli inequality for a quasiminimzer.
Definition 4.1. Let $\varphi \in \Phi_{w}(\Omega)$ and $K \geqslant 1$. A function $u \in W^{1, \varphi}(\Omega)$ is a local $K$ quasiminimizer of the $\varphi$-energy in $\Omega$ if

$$
\int_{\{v \neq 0\}} \varphi(x,|\nabla u|) d x \leqslant K \int_{\{v \neq 0\}} \varphi(x,|\nabla(u+v)|) d x
$$

for all $v \in W^{1, \varphi}(\Omega)$ with spt $v:=\overline{\{v \neq 0\}} \subset \Omega$.
In the next result we need the doubling near infinity.

Lemma 4.2 (Caccioppoli inequality for quasiminimizer ). Let $\varphi \in \Phi_{w}(\Omega)$ satisfy $(a D e c)_{q}^{\infty}$, $u$ be a local $K$-quasiminimizer in $\Omega$ and $2 B \subset \subset \Omega$. Then we have

$$
\begin{equation*}
\int_{B} \varphi(x,|\nabla u|) d x \lesssim \int_{2 B} \varphi\left(x, \frac{\left|u-u_{2 B}\right|}{\operatorname{diam} B}\right) d x+1 \tag{4.3}
\end{equation*}
$$

in the ball $B$, where the implicit constant depends only on $n, K$ and $(a D e c)_{q}^{\infty}$.
Proof. Denote $\kappa:=\operatorname{diam} B$. Let $t, s \in[1,2], s<t$. Also, let $\eta \in C_{0}^{\infty}(t B)$ be such that $0 \leqslant \eta \leqslant 1, \eta=1$ in $s B$, and $|\nabla \eta| \leqslant \frac{4}{(t-s) \kappa}$. Denote $w=-\eta\left(u-u_{2 B}\right)$ and $v:=u+w$. Since $u$ is a local $K$-quasiminimizer

$$
\int_{t B} \varphi(x,|\nabla u|) d x \leqslant K \int_{t B} \varphi(x,|\nabla v|) d x .
$$

We have

$$
|\nabla v| \leqslant(1-\eta)|\nabla u|+|\nabla \eta|\left|u-u_{2 B}\right| .
$$

Denote $a:=2^{q} L \geqslant 1$. By $(\mathrm{aDec})_{q}^{\infty}$ and $|\nabla \eta| \leqslant \frac{4}{(t-s)_{\kappa}}$, we get that

$$
\begin{aligned}
\varphi(x,|\nabla v|) & \leqslant \varphi\left(x, 2 \max \left\{(1-\eta)|\nabla u|, \frac{4\left|u-u_{2 B}\right|}{(t-s) \kappa}\right\}\right) \\
& \leqslant(\varphi(x, 2(1-\eta)|\nabla u|)+1)+\left(\varphi\left(x, \frac{8\left|u-u_{2 B}\right|}{(t-s) \kappa}\right)+1\right) \\
& \leqslant a \varphi(x,(1-\eta)|\nabla u|)+a+a^{3} \varphi\left(x, \frac{\left|u-u_{2 B}\right|}{(t-s) \kappa}\right)+a^{3} \\
& \leqslant a \varphi(x,(1-\eta)|\nabla u|)+a^{3} \varphi\left(x, \frac{\left|u-u_{2 B}\right|}{(t-s) \kappa}\right)+c .
\end{aligned}
$$

Combining the above inequalities, we find that

$$
\int_{t B} \varphi(x,|\nabla u|) d x \leqslant a K \int_{t B} \varphi(x,(1-\eta)|\nabla u|) d x+a^{3} K \int_{t B} \varphi\left(x, \frac{\left|u-u_{2 B}\right|}{(t-s) \kappa}\right) d x+K c|2 B| .
$$

By decreasing the set on the left hand side, we obtain

$$
\begin{align*}
& \int_{s B} \varphi(x,|\nabla u|) d x \\
& \quad \leqslant a K \int_{t B} \varphi(x,(1-\eta)|\nabla u|) d x+a^{3} K \int_{t B} \varphi\left(x, \frac{\left|u-u_{2 B}\right|}{(t-s) \kappa}\right) d x+K c|2 B| . \tag{4.4}
\end{align*}
$$

On the right-hand side, we have $\varphi(x,(1-\eta)|\nabla u|)=\varphi(x, 0)=0$ in $s B$, and so

$$
\int_{t B} \varphi(x,(1-\eta)|\nabla u|) d x=\int_{t B \backslash s B} \varphi(x,(1-\eta)|\nabla u|) d x \leqslant \int_{t B \backslash s B} \varphi(x,|\nabla u|) d x .
$$

Now we can use the hole-filling trick by adding $a K \int_{s B} \varphi(x,|\nabla u|) d x$ to both sides of (4.4), ending with $a K+1$ of the integral on the left-hand side, and $a K$ on the right. After we divide with $a K+1$, we have

$$
\int_{s B} \varphi(x,|\nabla u|) d x \leqslant \frac{a K}{a K+1} \int_{t B} \varphi(x,|\nabla u|) d x+\frac{a^{3} K}{a K+1} \int_{2 B} \varphi\left(x, \frac{\left|u-u_{2 B}\right|}{(t-s) \kappa}\right) d x+C .
$$

Since $1 \leqslant \frac{a K}{a K+1}+\frac{a^{3} K}{a K+1}$, this implies that

$$
\begin{aligned}
\int_{s B} \varphi(x,|\nabla u|)+1 d x \leqslant & \frac{a K}{a K+1} \int_{t B} \varphi(x,|\nabla u|)+1 d x \\
& \quad+\frac{a^{3} K}{a K+1} \int_{2 B} \varphi\left(x, \frac{\left|u-u_{2 B}\right|}{(t-s) k}\right)+1 d x+C .
\end{aligned}
$$

Now, as the function $(\varphi(x, t)+1)$ is doubling for all $t>0$, we can use a variant of the standard iteration lemma, Lemma 4.2 of [25], and get

$$
\int_{B} \varphi(x,|\nabla u|)+1 d x \lesssim \int_{2 B} \varphi\left(x, \frac{\left|u-u_{2 B}\right|}{\kappa}\right)+1 d x+C .
$$

The result follows after we subtract $|B|$ from both sides.
Lemma 4.5 (Gehring's lemma, [20]). Let $f \in L^{1}\left(B_{R}\right)$ be non-negative. Assume that $g \in$ $L^{q}\left(2 B_{R}\right)$ for some $q>1$ and that there exists $s \in(0,1)$ such that

$$
f_{B} f d x \lesssim\left(f_{2 B} f^{s} d x\right)^{\frac{1}{s}}+f_{2 B} g d x
$$

for every ball $B \subset \subset B_{R}$. Then there exists $t>1$ such that

$$
\left(f_{B_{R}} f^{t} d x\right)^{\frac{1}{t}} \lesssim f_{2 B_{R}} f d x+f_{2 B_{R}} g^{t} d x
$$

Now we are ready to prove our main result, which follows from the last three results.
Proof of Theorem 1.1. Let $p>1$ be such that $\varphi$ satisfies (aInc) ${ }_{p}$. Fix $s \in(1, p]$ with $s<$ $\frac{n}{n-1}$. Choose a ball $B_{R}$ such that $2 B_{R} \subset \subset \Omega$ and $\|\nabla u\|_{L^{\varphi}(2 B)}<1$. Now the Caccioppoli inequality (Lemma 4.2) yields for a local quasiminimizer $u$ and $B \subset \subset B_{R}$ that

$$
f_{B} \varphi(x,|\nabla u|) d x \lesssim f_{2 B} \varphi\left(x, \frac{\left|u-u_{2 B}\right|}{\operatorname{diam} B}\right) d x+C
$$

First adding 1 to the right-hand side, then using $(\mathrm{aDec})_{q}^{\infty}$ and finally the Sobolev-Poincaré inequality (Proposition 3.6) we get that

$$
f_{B} \varphi(x,|\nabla u|) d x \lesssim f_{2 B} \varphi\left(x, \beta_{3} \frac{\left|u-u_{2 B}\right|}{\operatorname{diam} B}\right)+1 d x+C \lesssim\left(f_{2 B} \varphi(x,|\nabla u|)^{\frac{1}{s}} d x\right)^{s}+C .
$$

With $g=C \chi_{\Omega}$, Gehring's lemma (Lemma 4.5) yields

$$
\left(f_{B_{R}} \varphi(x,|\nabla u|)^{t} d x\right)^{\frac{1}{t}} \lesssim f_{2 B_{R}} \varphi(x,|\nabla u|) d x+f_{2 B_{R}} C^{t} d x<\infty .
$$

Writing $\epsilon=t-1$, we see that $\varphi(\cdot,|\nabla u|)$ has higher integrability in the ball $B$.
Cover $\Omega^{\prime} \subset \subset \Omega$ with balls $B_{i}$ that satisfy the assumptions of the first part of the proof. Because $\Omega^{\prime}$ is compact, we can choose a finite subcover $\left\{B_{i}\right\}_{i=1}^{N}$. Now

$$
\left(f_{\Omega^{\prime}} \varphi(x,|\nabla u|)^{1+\varepsilon} d x\right)^{\frac{1}{1+\varepsilon}} \lesssim \sum_{i=1}^{N} f_{2 B_{i}} \varphi(x,|\nabla u|) d x+f_{2 B_{i}} C^{r} d x<\infty
$$

and therefore $\varphi(\cdot,|\nabla u|) \in L_{\text {loc }}^{1+\varepsilon}(\Omega)$.

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