CORRECTION



Correction to: Integrated Extremal Control and Explicit Guidance for Quadcopters

Evan Kawamura¹ • Dilmurat Azimov¹

Published online: 29 August 2020 © Springer Nature B.V. 2020

Erratum to: Journal of Intelligent Robotics System https://doi.org/10.1007/s10846-020-01211-2

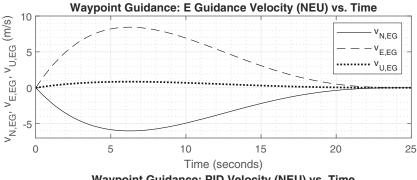
Due to oversight, an incorrect figure in Ref. [1] was printed for Fig. 17, but the original wording and description of Fig. 17 is correct. The correct Fig. 17 is below.

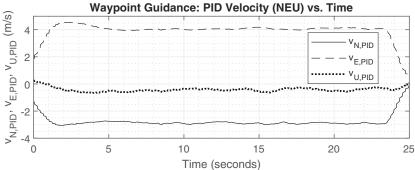
Fig. 17 Waypoint Guidance: E Guidance & PID Velocity Comparison vs. Time

References

 Kawamura, E., Azimov, D.: Integrated extremal control and explicit guidance for quadcopters. J Intell Robotic Sys, 1–31 (2020)

Publisher's Note Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.





The online version of the original article can be found at https://doi.org/10.1007/s10846-020-01211-2.

 ⊠ Evan Kawamura evankawa@hawaii.edu

Dilmurat Azimov azimov@hawaii.edu

Mechanical Engineering, University of Hawaii: Manoa, Holmes Hall, 2540 Dole Street, Honolulu, HI 96822, USA

