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Analyzing the Dynamics of Lung Cancer Imaging Data Using Refined Fuzzy Entropy Methods by Extracting Different Features

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ABSTRACT Lung cancer is the major cause of cancer-related deaths worldwide with poor survival due to the poor diagnostic system at the advanced cancer stage. In the past, researchers developed computeraided diagnosis (CAD) systems, which were greatly used by the radiologist for identifying the abnormalities and applied few features extracting methods. The physiology and behavior of various physiological systems can be best investigated using nonlinear dynamical measures for capturing the intrinsic dynamics, which is influenced due to multiple pathologies by the degradation of structural and functional components. As cancer images contain hidden information, which can be best analyzed using these dynamical measures. In this paper, we proposed multiscale sample entropy (MSE) with a mean and KD-tree algorithmic approach, multiscale permutation entropy (MPE), multiscale fuzzy entropy (MFE), and refined composite multiscale fuzzy entropy (RCMFE) with mean, variance, and standard deviation. The statistically significant results were computed to distinguish non-small-cell lung cancer (NSCLC) from SCLC by extracting morphological, texture, and elliptic Fourier descriptors (EFDs). The highest significant results obtained based on texture features using MFE with standard deviation give the P-value of 1.95E-50, morphological features using RCMFE with mean provide the P-value of 3.01E-14, and EFDs features using MFE with variance give the P-value of 1.04E-13. The results reveal that the improved complexity measures based on refined fuzzy entropy outperformed in analyzing the dynamics of lung cancer and will provide a new insight into extract meaningful hidden information present in the Lung cancer images, which will be very helpful to further distinguish NSCLC and SCLC for early diagnosis and prognosis.

INDEX TERMS Non small cell lung cancer (NSCLC), small cell lung cancer (SCLC), texture, morphological, multiscale fuzzy entropy (MFE), refined composite multiscale fuzzy entropy (RCMFE).

I. INTRODUCTION

The recent statistics of Lung cancer 2018 reveals that approximately 234,030 new cases of lung cancer are expected to be diagnosed and there would be 85% of whom will be non small cell lung cancer (NSCLC) [1], [2]. For detecting early NSCLC, there are two main approaches such as radiofrequency (RF) ablation and stereotactic body radiotherapy (SBRT). The two main types of Lung cancer are small cell lung carcinoma (SCLC) and non small cell lung carcinoma (NSCLC). Both of these types of lung cancer have different ways of spreading and treatment. The cancer containing the features of both of these types is called mixed small cell/ large cell cancer. NSCLC is more common than SCLC which spread and grows very slowly. Where SCLC is related to smoking and grows very quickly and forms tumors and spread widely in the body. The deaths due to the lung cancer is related to the total amount of cigarette smoked [3].

Lung cancer is the most prevalent cancer and the leading cause of cancer-related deaths worldwide, resulting in more than 1.4 million deaths annually [4], [5]. Evaluation of the microscopic histopathology slides by experienced pathologists is indispensable to establish the diagnosis [6], [7] and defines the types and subtypes of lung cancers, including the

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two major types of non small cell lung cancer: adenocarcinoma and squamous cell carcinoma [8], [9].

SCLC is an aggressive form of lung cancer which is directly associated with the cigarette smoked. Its increasing evidences has implicated proto-oncogenes, autocrine growth loops, and tumor-suppressor genes in its development. Therefore, SCLC treatment and prognosis are different from NSCLC. An early detection of NSCLC can be helpful for survival rate of 35 to 85% depending upon the type and stage of tumor. As most of the cancer cases are detected late due to which the overall five-year survival rate for NSCLC is only 16%. Moreover, for SCLC standard therapy is chemotherapy which elicits a response in over 60% of SCLC patients. Therefore, the cancer returns within few months which result in an abysmal overall five-year survival rate of 6% for SCLC. These survival rates for both type of cancer have a little change for the past two decades.

The most common and frequently used imaging technique to diagnose the cancer is computed tomography (CT) [10]. The CT is one of the efficient technique used to diagnose the pulmonary nodules [11]. The structural and functional information about the human body is obtained using the X-rays. The CT image quality is influenced by the radiation dose. The performance of different machine learning algorithms that are useful to lung cancer prediction and prognosis are endeavored to explained and evaluated by [12]. It is proved that machine learning methods are commonly used to improve the performance or predictive accuracy of most prognosis, especially when compared to conventional statistical or expert-based systems. A survey of machine learning methods used in cancer prediction showing the types of cancer, clinical endpoints, choice of algorithm, performance and type of training data are discussed in detail. The following machine learning algorithm benefits and assumptions and limitations are discussed in method section: Decision Tree, Naïve Bayes, K-Nearest neighbor, Neural Network, Support Vector Machine (SVM) and Genetic Algorithm.

Data mining classification techniques on Lung cancer diagnosis are proposed by [13]. The Rule set classifier, Decision Tree, Neural Network and Bayesian Network classification algorithms are used for Lung Cancer analysis. From the result it was identified that Naïve Bayes algorithm produced better results than the other algorithms. Using fuzzy rules, [14] proposed a template matching technique based on genetic algorithms (GA) template matching (GATM) for detection of nodules existing within the lung area. In their work, GA was used to determine the target position in the observed image efficiently and to select an adequate template image from several reference patterns for quick template matching.

Computer-aided diagnosis (CAD) systems are efficient schemes that have been developed for the detection and characterization of various lesions in the field of the diagnosis of lung cancer. CAD system is mainly used for detection of lung cancer. The system deals with the problem of developing a computer based system for the extraction of maximum features from the segmented suspicious area from the lung X-ray image and these properties can be used to classify lung tumor as benign or malignant from the X-ray image directly [15].

Researchers in the past employed different features extracting strategies such as morphological, texture, scale invariant Fourier transform (SIFT), elliptic Fourier descriptors (EFDs), geometric, shape based features [16]-[21] for medical imaging problems. The existing techniques have some limitations as these methods are competitively expensive as most the important information is hidden in the cancer images in the region of interest which is of complex nature. Moreover, growth and proliferation of cancer cells also change the structural components thereby effecting the health of individuals and alter the complexity of the behavioral and physiological systems output. Thus, this problem can be more fully analyzed using the complexity based dynamical measures for further improving the detection performance. The physiological behavior of various physiological systems can be studied by examining the complexity of the systems [22]–[24] including behavior and physiological agin [25], [26], using nonlinear dynamical measures [27]-[30]. The complexity has been inherited with several other concepts such as randomness, entropy, and information theory [30]-[34]. Lipsitz [35] proposed the complexity reduced for control or physiological systems with aging disease. This reduction in complexity is due to the underlying structural or functional changes in the organization of the system. The behavior and physiological systems are influenced by multiple factors and their complexity is examined using several methods. Researchers computed various complexity-based methods such as approximate entropy [30], spectral analysis [36]. Lyapunov exponent [37], detrended fluctuation analysis [38] to quantify the dynamics of various pathological systems. Hussain et al. [39], [40] recently employed MSE with KD tree algorithm and Refined Fuzzy entropy approaches in quantifying the dynamics of various physiological systems, the results obtained using these approaches outperformed than the traditional entropy methods.

II. MATERIAL AND METHODS

A. DATA SET

Datasets were taken from a publicly available database www.giveascan.org provided by Lung Cancer Alliance. The Lung Cancer Alliance (LCA) is the only national nonprofit organization providing patient support and advocacy exclusively to those living with or at risk for lung cancer and aim of this web-based repository is to facilitate in research purposes. Database Images are in Digital Imaging and Communications in Medicine (DICOM) format. This database comprises 76 patients with total of 945 images i.e. 568 from SCLC subjects and 377 from NSCLC subjects.

B. FEATURES EXTRACTION

For regression and classification, the most important step is to extract the most relevant feature. The detection performance in machine learning classification problems is relying on the type of features extracted. In the past, researchers extracted different features e.g. hybrid features for detecting colon cancer [17]–[19]. Hussain et al. and co-workers recently extracted hybrid features based on texture, morphological, Scale invariant Fourier transform (SIFT), Elliptic Fourier descriptors (EFDs), entropy based complexity features for detecting prostate cancer, lung cancer, breast cancer and brain tumor [18], [20], [41]–[43]. Moreover, the complex dynamics of various physiological systems such as arrhythmia detection, epileptic seizure detection, Alzheimer disease, Alcoholism etc. [21], [40], [39], [44]–[49] have been studied. In this study, we first extracted morphological, texture and EFDs features and then employ the complexity measures to quantify the dynamics of lung cancer imaging data.

1) MORPHOLOGICAL FEATURES

The shape and structure characteristics of an image are determined using morphological features. In the past researchers used morphological features for computer-aided diagnostic systems. Researchers computed morphological features for automated prostate cancer localization [50], quantifying phenotypes for image analysis [51]-[53], detecting lung cancer [54], detection of seed of wild castor oil plants [55], colon cancer detection [18]. Recently Hussain et al. computed morphological features from prostate cancer images and computed the associations among these features to determine the strength between these features [56]. Morphological feature extraction module (FEM) takes input inside the shape of binary cluster and finds associated components in the clusters [57]. Researchers [18] in the past extracted nine morphological features which are: Perimeter (p), Eccentricity (y), location (a), Convex area (x), Euler quantity (l), Compactness (o), Orientation (e), duration of fundamental (m1), and Minor Axes (m2) are calculated for every issue of cluster. In this study, we extracted 14 different morphological features which are detailed and reflected in Figure 3 and Table 4 at Annex-A.

2) TEXTURE FEATURE

In previous studies, the texture features are most widely used in solving classification issues [58]-[60], particularly to classify the colon biopsie [61], [62], prostate cancer detection [20] and brain tumor detection [42]. Texture characteristics have been efficiently utilized in solving class related problems. The texture features are calculated from grey level cooccurrence matrix (GLCM) that covers the spatial relationship between pixels (of image). Each entry (u,v)th in the GLCM defines how frequently the pixel with intensity value *u* co-occur in a specified relationship with pixel having intensity value of v. The relationship between the pixels can be computed using (i) relative distance between neighboring pixels and pixels of interest and (ii) their orientation θ . Normally, the θ have four directions (0°45°90°135°). There are fifteen features which can be obtained from GLCM including Entropy, Angular 2D moment, comparison,

correlation, nearby homogeneity, color, variance, common, Sum, prominence, difference entropy, sum entropy, distinction variance, sum variance, facts degree of correlation [63]. In this study, we extracted texture features which are reflected in Figure 3 and Table 5 at Annex-A.

3) ELLIPTIC FOURIER DESCRIPTORS (EFDs) FEATURE

To distinguish the elliptic shapes, the EFDs are most useful features. EFDs characteristics have been correctly used by many researchers for the characterization of closed shapes. Kuhl and Giardina [64] in 1982 introduced EFDs features to classify the solid objects such as box and car etc. Moreover, in pattern recognition systems [65], [66], EFDs features are most widely used. EFD method made up of an expansion of a shape as sum of ellipse. The Fourier Descriptors never change with translation of the shape and rotation. Two stages are required in computing EFDs features. In the first stage, the elliptic features are recognized in the white bunch of images. In the secondary phase, the elliptic object is arranged considering region along with EFDs of upper most N object be equal to the aimed Harmonic level Y. EFDs depend on chain codes by estimating the close shape by grouping of eight institutionalized line portions, are invariant to expansion, interpretation, rotation and beginning point of a closed shape. To obtain EFDs harmonic level Y, four coefficients i.e. t, u, v and w against every Harmonic level have computed detailed in [18], [20] as below:

$$t_{i} = [t_{1}t_{2}t_{3}, \dots, t_{N}]i^{P} \text{ Where } i = 1, 2, 3, \dots N$$

$$u_{i} = [u_{1}u_{2}u_{3}, \dots, u_{N}]i^{P}$$

$$v_{i} = [vv_{2}v_{3}, \dots, v_{N}]i^{P}$$

$$w_{i} = [ww_{2}w_{3}, \dots, w_{N}]i^{P}$$
(1)

where $t_i u_i$, v_i and w_i vectors contain t, u, v and w Fourier coefficients of ith primitive up to harmonic level N. The average of these vectors is calculated as following: $\bar{t} = \frac{1}{N} \sum_{i=1}^{N} t_i$, $\bar{u} = \frac{1}{N} \sum_{i=1}^{N} u_i$, $\bar{v} = \frac{1}{N} \sum_{i=1}^{N} V_i$ and

$$\bar{w} = \frac{1}{N} \sum_{i=1}^{N} w_i \tag{2}$$

The Final elliptic feature vector (z) is determine by combining the above equation

$$z = [\bar{t}^P \bar{u}^P, \bar{v}^P, w^P]^P \tag{3}$$

The Fourier series f(x) is described by the equation:

$$f(x) = \frac{1}{2}n_0 + \sum_{a=1}^{\infty} [n_a \cos(nx) + m_a \sin(nx)]$$
(4)

The elliptic Fourier coefficients of the n-th harmonic (an, bn, cn, dn) detailed in [67] are given as:

$$a_n = \frac{T}{2n^2\pi^2} \sum_{p=1}^k \frac{\Delta x_p}{\Delta t_p} \left[\cos\left(\frac{2n\pi t_p}{T}\right) - \cos\left(\frac{2n\pi t_{p-1}}{T}\right) \right]$$
(5)

$$b_n = \frac{T}{2n^2\pi^2} \sum_{p=1}^k \frac{\Delta x_p}{\Delta t_p} \left[\sin\left(\frac{2n\pi t_p}{T}\right) - \sin\left(\frac{2n\pi t_{p-1}}{T}\right) \right]$$
(6)

$$c_n = \frac{T}{2n^2\pi^2} \sum_{p=1}^k \frac{\Delta y_p}{\Delta t_p} \left[\cos\left(\frac{2n\pi t_p}{T}\right) - \cos\left(\frac{2n\pi t_{p-1}}{T}\right) \right]$$
(7)

$$d_n = \frac{T}{2n^2\pi^2} \sum_{p=1}^k \frac{\Delta y_p}{\Delta t_p} \left[\sin\left(\frac{2n\pi t_p}{T}\right) - \sin\left(\frac{2n\pi t_{p-1}}{T}\right) \right]$$
(8)

T is the period (the interval), n is the number of the harmonic, p is the index of the chain link, k is the number of chain links, and tp and tp-1 are the lengths of the chain at the pth link.

The truncated Fourier approximation to a closed contour can be written as:

$$x(t) = A_0 + \sum_{n=1}^{N} X_n$$
(9)

$$y(t) = C_0 + \sum_{n=1}^{N} Y_n$$
 (10)

where components of projections X_n and $Y_n(1 \le n \le N)$ are

$$X_n(t) = a_n \cos\frac{2\pi nt}{T} + b_n \sin\frac{2\pi nt}{T}$$
(11)

$$Y_n(t) = c_n cos \frac{2\pi nt}{T} + d_n sin \frac{2\pi nt}{T}$$
(12)

And A_0 and C_0 are the DC components of the Fourier series.

The contours are chain-coded represented by x and y coordinates of ordered points. Consider contour between the (i-1)th and ith chain-coded point is linearly interpolated and contour length from starting point to the pth point and perimeter to the contour are represented by tp and T respectively, then

$$t_p = \sum_{i=1}^{p} \Delta t_i \tag{13}$$

where Δt_i is the distance between (i-1)th and ith point.

The x and y coordinates of pth points are:

$$x_p = \sum_{i=1}^p \Delta x_i \tag{14}$$

$$y_p = \sum_{i=1}^{p} \Delta y_i \tag{15}$$

where Δx_i and Δy_i are the distance along x and y axis between (i-1)th and ith points. Thus, elliptic Fourier expansion of the coordinates on the contour are given by:

$$x_p = A_0 + \sum_{n=1}^{\infty} \left(a_n \cos\left(\frac{2n\pi t_p}{T}\right) + b_n \sin\left(\frac{2n\pi t_p}{T}\right) \right) \quad (16)$$

$$y_p = C_0 + \sum_{n=1}^{\infty} \left(c_n \cos\left(\frac{2n\pi t_p}{T}\right) + d_n \sin\left(\frac{2n\pi t_p}{T}\right) \right) \quad (17)$$

The Fourier series describe by the above equation approximates the true function arbitrarily well on any finite interval. If one replaces the infinite sum with a finite one, from n = 1 to k, this is called the kth harmonic; the higher the value of k, the better the approximation.

In order to modify ellipse to approximate the closed contour, below is the equation that gives the nth Elliptic Fourier Descriptor.

$$\frac{(d_n^2 + c_n^2)X_n^2 + (a_n^2 + b_n^2)Y_n^2 - 2X_nY_n(a_nc_n + b_nd_n)}{(a_nd_n - b_nc_n)} = 1 \quad (18)$$

C. NONLINEAR DYNAMICAL ANALYSIS

In the present study, we extracted morphological, texture and EFDs features from lung cancer images and then apply the following complexity-based approaches to quantify the dynamics of lung cancer images.

1) REFINED MULTISCALE FUZZY ENTROPY

Entropy is broadly used to measures what has been generally utilized in physiological signal examination. One of the mostly used entropy-based methodologies is sample entropy, which is relatively robust to noise and the other extensively used entropy method is fuzzy entropy. Recently, these two techniques have most widely used in many applications. In spite of the fact that sample entropy is slightly faster than fuzzy entropy, however, later is more stable to the data length [40], [68], [69].

In fuzzy entropy, for the time series $x = (x_1, x_2, ..., x_n)$, embedding dimension h, and tolerance t,

 $S_r^h = \{x_r, x_{r+1}, \dots, x_{r+h-1}\} - x0_r \text{ is formed where } x0_r = \sum_{j=0}^{h-1} \frac{x_{t+j}}{h}, \text{ the distance between each of } S_{r1}^h \text{ and } S_{r2}^h \text{ is defined as: } d_{ri,r2} = d\left[S_{r1}^h, S_{r2}^h\right] = \max\left[\left|S_{r1+m}^h - S_{r2+m}^h\right| : 0 \le h \le r-1 \text{ and } r_1 \ne r_2\right].$

For Fuzzy entropy the power and tolerance are denoted as n and t, the similarity amount $d_{ri,r2}$ is computed through a fuzzy function μ (d_{rir2} , n, t) as exp ($-(d_{ri,r2})^n/t$) the function α^h is defined as:

$$=\frac{1}{N-h}\sum_{r_{1}=1}^{N-h}\frac{1}{N-h-1}\sum_{r_{2}=1,r_{1}\neq r_{2}}^{\alpha^{n}(x,n,t)}\exp\left(-\left(d_{ri,r2}\right)^{n}/t\right)$$
(19)

Finally, the Fuzzy entropy of the signal is computed as the negative natural logarithm of the ratio of α^{h} and α^{h+1} .

$$FE(x, h, n, t) = -\ln\left(\alpha^{h+1}/\alpha^{h}\right)$$
(20)

The complication of a system can be calculated with numerous nonlinear dynamical procedures such as entropy related techniques. These techniques are used to identify the healthy and non-healthy groups to quantity the complexity of the biological actions.

2) MULTISCALE SAMPLE ENTROPY (MSE)

In the past, researchers quantified the complex dynamics of physiological and neurophysiological signals by applying entropy measures. One of the most popular time series is sample entropy which is computed as an unbiased estimator of the conditional probability that two timeseries with m consecutive points will remain similar when there is one or more consecutive points are added (where m denotes the embedding dimension). Sample entropy was derived from the developed approaches of Grassberger and co-workers [70]–[73].

Sample entropy was used to mine information in a time sequence and measurements of the organized structure was agreed by testing the repeated patterns of varying length. It is calculated as a negative average natural logarithm of conditional probability.

Consider a time sequences a (1), a (2), a (3), a (4)... a (N), where N is the data length. Sample entropy can be calculated as follow:

$$A(i) = A(i), A(i+1), A(i+2)...(Ai+m-1)].$$
 (21)

where $i = 1, 2, 3 \dots N - m + 1$.

The distance d [A(i), A(j)] between two series A(i) and A(j) is calculated as:

$$[A (i), A (j)] = \max[|a(i + r) - a(j + r)|](11)$$

where $r = 0, 1, 2 \dots m - 1$.

And j = 1, 2, 3... N - m + 1; but $j \neq i$.

Count d [A (i), A (j)] which is smaller than the given threshold, then calculated the ratio of this number with total $\rm N-m$ as

$$R_{i}^{m}(s) = \frac{\left\{number \text{ of } d\left[A\left(i\right), A\left(j\right)\right] < s\right\}}{N-m}$$
(22)

Compute $\mathbf{R}_{i}^{m}(s)$ for all I as:

$$R^{m}(s) = \frac{\sum R_{i}^{m}(s)}{N - m + 1}$$
(23)

In order to obtain increment in dimension, increase one to number of dimensions of the vector. Repeat the above steps I to IV until $R^{m+1}(s)$ is obtained.

The sample entropy is calculated as:

$$SamEN(N, s, m) = -\ln\left[\frac{R^{m+1}(s)}{R^m(s)}\right] = \ln\frac{w_d}{w_n} \qquad (24)$$

As discussed earlier, Sample entropy methods provide limited performance for complex data, and is not appropriate for a complex time sequences whose features are calculated at various scales. MSE is calculated at numerous time scales. It has been established using coarse grained time series. For a one-dimensional time series,

$$u = \{u_1, u_2, u_3, \dots u_n\}$$

The following equation calculate the coarse-grained time sequences $f(\tau)$ at scale τ

$$f_a^{\tau} = \frac{1}{\tau} \sum_{b=(a-1)\tau+1}^{a\tau} u_b, \quad 1 \le a \le \frac{N}{\tau}$$
 (25)

3) SAMPLE ENTROPY WITH K-D TREE ALGORITHMIC APPROACH

The sample entropy was proposed by [74] is a modified form of approximate entropy. The sample entropy in comparison to approximate entropy shows good features line trouble free implementation and independent of data length. Manis (2008) [75] proposed K-D tree algorithmic approach using approximate entropy. An improved version of K-D tree algorithm was proposed by [76] that can create the multiple randomized K-d trees. Pan *et al.* (2011) [77] developed new K-d tree algorithm based on sample entropy detailed in [39], which is more efficient with respect to performance, space and time complexity using following steps:

Step 1. Transform the original discrete time series to a special point set from $x = \{x1, x2, x3, \dots, xN\}$

Step 2. The d-dimensional K-d tree is constructed using N-m points for which total cost is O (N long N) and memory is O(N)

Step 3. Range query; For, d-dimensional K-d tree search the time cost is $NO(N^{1\frac{1}{d}})$ for N queries and memory cost is O(N)

4) MULTISCALE PERMUTATION ENTROPY (MPE)

Permutation entropy states the local order structure of the time series, which can give a computable complexity measure for a dynamical time series. Permutation entropy was presented as a computational proficient technique for extracting the data from complex framework. At each time's' of a given a time series [78].

$$A = (a_1 + a_2 + a_3 \dots a_n)$$
(26)

A vector collected as the mth preceding values is formed:

$$U \to (A_{\tau}, A_{\tau+1}, \dots, A_{\tau+(p-2)}, A_{\tau+(p-1)})$$
 (27)

where p is called embedding dimension and represent how information is present in a vector and τ is time delay. For a given embedding dimension there will be p! Possible permutation p.

Permutation entropy follows the concept of Shannon entropy by examining the relative frequency of patterns generated form time series. The permutation entropy (PE) is defined as:

$$PerEn = -\sum_{i=1}^{p} \pi_i \ln \pi_i$$
(28)



FIGURE 1. Coarse grained time series procedure.

Permutation entropy depends on the choice of embedding dimension 'p' and time delay ' τ '. [79] recommended that value of embedding dimension 'p' should be $3 \le p \le 7$ and time delay $\tau = 1$. Normalized permutation entropy is calculated by the following formula:

$$NPerEn = -\frac{PerEn}{\ln p!}$$
(29)

where $\ln p!$ represents extreme PE value.

MPE incorporates two procedures [80] First, a coarsegraining process detailed in [44] is applied to a time series as reflected in the Figure 1. For a given time series $(a_1, a_2, a_3, ..., a_n)$, a repeated coarse-grained time series is formed by averaging a successively increasing number of data points in non-overlapping windows. Each element of a multiple coarse-grained time series m_i^v is computed as:

$$m_j^v = 1/v \sum_{i=(j-1)v+1}^{jv} a_i$$
 (30)

v defines the scale factor and $1 \le j \le L/v$. The coarsegrained time series is simply the original time series when v = 1.

Now, PE is computed for each coarse-grained time series and plotted as a function of the scale factor v. To calculate the permutation of a coarse-grained time series $w_j, v_t = [w_t, w_{t+1}, \ldots, w_{t+p-1}]$ is created with the embedding p and then organized in an increasing order: $w_{t+j_1-1} \leq w_{t+j_2-1}, \ldots \leq w_{t+j_n-1}$. There are p! Possible patterns, called permutations.

Let f(x) defines the frequency in the time series, its relative frequency is:

$$\boldsymbol{R}(\boldsymbol{x}) = \frac{f(\boldsymbol{x})}{L/\nu^{-}p + 1}$$
(31)

The permutation entropy is computed as follow:

$$PerEn = -\sum_{i=1}^{p} p(\pi_i) \ln p(\pi_i)$$
(32)

Small Cell

FIGURE 2. SCLC and NSCLC.

If the value of PE = 1 than all permutations have an equal chance to occur and if the PE = 0 then it shows that the time series is regular.

III. RESULTS

In this study, we first extracted texture, morphological and EFDs features from Lung cancer images then applied the entropy-based complexity measures such as Multiscale sample entropy (MSE), multiscale permutation entropy (MPE), Multiscale sample entropy based on KD-tree algorithmic approach, Multiscale Fuzzy entropy (MFE) based on mean, variance and standard deviation, refined composite Multiscale Fuzzy entropy (RCMFE) based on mean, variance and standard deviation.

In Table 1, KD- Tree algorithm was employed to distinguish SCLC group with NSCLC using different features which include morphological, texture, and EFD. The most significant result using KD Tree algorithm for morphological features were obtained at scale 1 having minimum P-value = 4.43E-11 with mean \pm SD = 0.2749 \pm 0.1453 for NSCLC and mean \pm SD = 0.2179 \pm 0.0768 for SCLC and is more significant with other values. For texture features we get most significant result at scale 3 having P-value = 3.51E-24 with mean \pm SD = 0 \pm 0 for NSCLC and mean \pm SD = 0.3638 ± 0.5112 for SCLC and is more significant with other values. At scale 5, 6, 7 no P- value appear shows no separation between groups. Similarly, for EFD features, we obtained most significant result at scale 7 having P- value = 2.06E-06 with mean \pm SD = 0.6413 ± 0.5393 for NSCLC and mean \pm SD = 0.8532 \pm 0.4637 for SCLC and is more significant with other values, respectively using K-D tree algorithmic approach as reflected in Table 3.

If we compare mean value of both classes using Morphological feature NSCLC exhibit higher complexity than SCLC subjects. As reflected in Table 3, by employing Multiscale sample entropy (MSE) and extracting morphological features, the NSCLC (0.4050) exhibit higher complexity than SCLC (0.3397). Similarly, by employing MSE

	MSE with KD tree algorithmic approach									
	Morphological features			Texture	Texture features			EFDs features		
Scale	NSCLC	SCLC	P-value	NSCL C	SCLC	P-value	NSCL C	SCLC	P-value	
	Mean ± SD	Mean ± SD		Mean ± SD	Mean ± SD		Mean ± SD	Mean ± SD		
1	0.2749 ± 0.1453	$0.2179 \\ \pm \\ 0.0768$	4.43E- 11	0.2007 ± 4.7279E -16	0.2007 ± 4.7279E- 16	-	1.0828	= 1.3950 ± 0.7179	8.88E- 05	
2	0.2742 ± 0.1454	0.2277 ± 0.0923	8.09E- 08	0.1016 ± 0.3660	0.4348 ± 0.5352	6.21E- 16	1.0509 ∃ 0.8748	= 1.3386 ± 0.7725	8.16E- 05	
3	0.2895 ± 0.1550	0.2496 ± 0.1179	3.52E- 05	0 ± 0	0.3638 ± 0.5112	3.51E- 24	1.0354 ± 0.8817	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	7.92E- 05	
4	0.3233 ± 0.1680	0.2815 ± 0.1413	1.40E- 04	0 ± 0	0.1857 ± 0.3963	1.24E- 12	1.0459± 0.8772	± 1.3442 ± 0.7678	6.16E- 05	

TABLE 1. Distinguishing NSCLC and SCLC group using KD -tree algorithm for morphological, texture and EFD features.

TABLE 2. Distinguishing NSCLC and SCLC group using MFE (variance) entropy for morphological, texture and EFD features.

	MFE with variance								
	Morphological features			Texture features			EFDs features		
cale	NSCLC	SCLC	P-value	NSCLC	SCLC	P-value	NSCLC	SCLC	P-value
Š	Mean ± SD	Mean ± SD		Mean ± SD	Mean ± SD		Mean ± SD	Mean ± SD	
2	0.1641 ± 0.5056	0.0029 ± 0.0291	2.55E-12	-0.9163 ± 1.1292 E-07	-0.9163 ± 4.2841E- 06	4.19E- 40	-6.4950 ± 5.2877	-4.3074 \pm 2.0975	2.94E- 10
3	3.1974E- 04 ± 9.9734E- 04	0 ± 0	3.03E-07	-0.4055 ± 1.7035 E-07	-0.4055 ± 6.2920E- 06	3.25E- 36	-1.5283 ± 3.7878	-2.1017 ± 3.5686	5.80E- 06
4	-	-	-	1.0624 E-07 ± 3.6932 E-07	3.9849E- 06 ± 8.5656E- 06	4.30E- 33	0.2180 ± 2.1232	0.0522 ± 1.4439	2.16E- 01
5	-	-	-	-	-	-	$2.1503 \pm \\ 4.3693$	$0.0920 \\ \pm \\ 0.6323$	1.04E- 13

and computing texture features a higher complexity of NSCLC (1.7964) than SCLC (1.5720). Moreover, NSCLE (2.0266) exhibit higher complexity than SCLC (1.8460) by extracting EFDs features and applying MSE. These findings are consistent with the previous studies [81]–[85] and [39], [44], [45], [48].

In Table 2, MFE based on variance was employed to distinguish SCLC group from NSCLC. We got most significant result at scale 2 for morphological feature having P-value (2.55E-12) with mean \pm SD = 0.1641 \pm 0.5056 for NSCLC and mean \pm SD = 0.0029 \pm 0.0291 for SCLC. Similarly, we get significant result for Texture feature at scale 2 having

TABLE 3. Distinguishing NSCLC and SCLC group using different entropy measures reflecting only optimal results based on morphological, texture and EFD features.

	Multiscale Sample entropy								
Scale	Morphological features			Texture features			EFDs features		
	NSCLC	SCLC	P- value	NSCLC	SCLC	P- value	NSCL C	SCLC	P- value
	Mean ± SD	Mean ± SD		Mean ± SD	Mean ± SD		Mean ± SD	Mean ± SD	
2	0.4050± 0.149	0.3397 ± 0.036	5.21E- 11	1.7964 ± 0.677	$\begin{array}{c} 1.572 \pm \\ 0.553 \end{array}$	5.48E- 07	$\begin{array}{c} 2.0266 \\ \pm \ 0.416 \end{array}$	1.846 ± 0.2001	4.08E -07
			Μ	ultiscale P	ermutation	ı Entropy	7		
2,1,1	1.373 ± 0.064	1.386± 2.66E- 15	2.50E- 03	2.151± 0.114	2.1800± 0.066	7.58E- 04	$\begin{array}{c} 2.218 \pm \\ 0.192 \end{array}$	2.112 ± 0.108	3.78E -12
			MSE u	sing KD-tr	ee Algorit	hmic app	roach		
1, 2,7	$\begin{array}{c} 0.275 \pm \\ 0.145 \end{array}$	$\begin{array}{c} 0.218 \pm \\ 0.076 \end{array}$	4.43E- 11	$\begin{array}{c} 0.102 \pm \\ 0.366 \end{array}$	0.434 ±0.535	6.21E- 16	0.641 ± 0.539	$\begin{array}{c} 0.853 \pm \\ 0.464 \end{array}$	2.06E -06
				MI	FE (Mean)				
1, 1,5	0.082±0.085	0.107 ± 0.042	3.01E- 14	-1.610± 0.002	-1.618 ± 0.011	9.81E- 34	1.502 ± 1.309	$\begin{array}{c} 2.021 \pm \\ 0.809 \end{array}$	2.46E -09
	MFE (Variance)								
2,3,5	$\begin{array}{c} 0.164 \pm \\ 0.506 \end{array}$	0.003 ± 0.029	2.55E- 12	-0.406 ± 1.703E- 07	-0.406± 6.292E- 06	3.25E- 36	2.150 ± 4.369	$\begin{array}{c} 0.092 \pm \\ 0.632 \end{array}$	1.04E -13
		-		N	IFE (SD)				
2,2,2	$\begin{array}{c} 0.238 \pm \\ 0.649 \end{array}$	0.014± 0.039	1.16E- 10	-0.916 ± 1.541E- 04	-0.915± 0.001	1.95E- 50	$\begin{array}{c} 0.554 \pm \\ 1.100 \end{array}$	$\begin{array}{c} 0.049 \pm \\ 0.262 \end{array}$	1.82E -12
	RCMFE (Mean)								
1,1,2	0.0820 ± 0.1065	$0.0297 \\ \pm \\ 0.0420$	3.01E- 14	-1.6104 ± 0.0019	$1.6183 \\ \pm \\ 0.0106$	9.81E- 34	-2.1451 ± 1.3111	-2.6228 ± 0.7580	3.89E -05
	RCMFE (Variance)								
2, 3,3	0.155 ± 0.414	0.004 ± 0.037	1.99E- 12	1.129E- 07 ± 3.859E- 07	4.548E- 06 ± 9.942E- 06	6.90E- 28	-0.4940 ± 1.4705	-0.926± 1.616	7.23E -05
	RCMFE (SD)								
2, 4,3	$\begin{array}{c} 0.199 \pm \\ 0.440 \end{array}$	0.013± 0.051	9.55E- 12	0.694 ± 5.584E- 04	0.696± 0.004	1.67E- 30	-0.690± 0.381	-0.892 ± 0.400	4.45E -07

P-value (4.19E-40) with mean \pm SD = -0.9163 \pm 1.1292E-07 for NSCLC and mean \pm SD = -0.9163 \pm 4.2841E-06 for SCLC. For EFD features we get significant result at scale 5 having P – value (1.04E-13) with mean \pm SD = 2.1503 \pm 4.3693 for NSCLC and mean \pm SD = 0.0920 \pm 0.6323 for SCLC.



FIGURE 3. Schematic diagram for analyzing the dynamics of lung cancer imaging data by extracting different features and employing entropy-based complexity measures.

As depicted in Table 3, by applying MSE with K-D tree algorithmic approach and extracting morphological features, NSCLC (0.275) exhibit higher entropy than SCLC (0.218). However, in case of texture and EFDs features, SCLC (0.434, 0.853) exhibit higher entropy values than NSCLC (0.102, 0.641) respectively.

The Table 3, we first extracted different features such as texture, morphological and EFDs from lung cancer images and then applied complexity-based measures such as MSE, MPE, MSE with KD tree algorithmic approach, MFE (with mean, variance & SD) and RCMFE (with mean, variance and SD) at multiple temporal scales to distinguish NSCLC from SCLC images. The highest significant results using MSE by extracting morphological features was obtained at scale 2 with P-value (5.21E-11), texture features with p-value (5.48E-07), and EFDs features with P-value (4.08E-07). By employing MPE the highest significant separation was obtained by extracting morphological features was obtained at scale 2 with P-value (2.50E-03), texture features at scale 1 with P-value (7.58E-04), and EFDs features at scale 1 with P-value (3.78E-12). Likewise, using MSE with KD tree algorithmic approach, the highest significant results were obtained by extracting morphological features at scale 1 with P-value (4.43E-11), texture features at scale 2 with P-value P



FIGURE 4. Mean values for NSCLC and SCLC subjects by extracting morphological, texture and EFDs features and employing different complexity measures.

P-value (6.21E-16) and EFDs features at scale 7 with P-value (2.06E-06). By employing the MFE with mean, the highest significant results were obtained by extracting morphological features at scale 1 with P-value (3.01E-14), texture features at scale 1 with P-value (9.81E-34) and EFDs features at scale 5 with P-value (2.46E-09). Likewise, by employing MFE with variance, the highest detection results were obtained by extracting morphological features at scale 2 with P-value (2.55E-12), texture features at scale 3 with P-value (3.25E-36), and EFDs features at scale 5 with P-value (1.04E-13). Moreover, by employing MFE with standard deviation, the highest detection performance was obtained by extracting morphological features at scale 2 with P-value (1.16E-10), texture features at scale 2 with P-value (1.95E-50), and EFDs features at scale 2 with P-value (1.82E-12). To distinguish the NSCLC from SCLC, we employed RCMFE with mean, variance and standard deviation. By employing RCMFE with mean, the highest significant results were obtained at scale 1 using morphological features with P-value (3.01E-14), texture features at scale 1 with P-value (9.81E-34) and EFDs features with P-value (3.89E-05). Likewise, detection performance on the basis of significant results by employing RCMFE with variance was obtained at scale 2 by extracting morphological features with P-value (1.99E-12), texture features at scale 3 with P-value (6.90E-28), EFDs features at scale3 with P-value (7.23E-05). Similarly, the highest performance using RCMFE with standard deviation was obtained using morphological features at scale 2 with P-value (9.55E-12), texture features at scale 4 with P-value (1.67E-30) and EFDs features at scale 3 with P-value (4.45E-07).

The most commonly used types of NSCLC [86] are stated below:

Adenocarcinomas is a common kind of lung cancer seen in Cigarette smoker and in non-smokers. It rises to take place in the edge of the lungs which is due to the addition of filters in cigarettes preventing large particles from entering the lungs. Adenocarcinoma have the capacity to grow slower and a greater chance to be detect before it is spread.

Squamous cell carcinomas more frequent as compared to adenocarcinomas. Squamous cell tumors rise utmost often in the middle chest area. This kind of lung cancer extremely stays inside the lung. These cell carcinomas are also linked to smoking.

Large cell carcinomas, occasionally mentioned as undistinguishable cancer, are the smallest common kind of NSCLC. This type of cancer has a higher chance to be spread on distant places but slowly. The NSCLC and SCLC visual information is shown in the Figure 2 below:

The Figure 3 illustrate the schematic flow of our model. In the first step, we converted the RGB images to grey color. We extracted texture, morphological and EFDs features from NSCLC and SCLC images. The texture features comprised of contrast, correlation, dissimilarity, energy, entropy, homogeneity, mean, variance, standard deviation, kurtosis, and root mean square (RMS). Moreover, the morphological features comprised of area, perimeter, maximum radius, minimum radius, eccentricity, Equidiameter, Elongatedness, entropy, circulatory I, circulatory II, dispersion, standard deviation of image and shape index and EFDs features which are rely on chain code by approximating shape of closed contour by a sequence of eight standardized line segments and are invariant to translation, dilation, rotation and starting point of contour. We then applied the complexity measures such as multiscale sample entropy (MSE) with mean and KD tree algorithm approach, multiscale permutation entropy (MPE), multiscale fuzzy entropy (MFE) and Refined composite multiscale fuzzy entropy (RCMFE) with mean variance and standard deviation.

The mean values at selected scales were computed as reflected in Table 3 and Figure 4. Mostly, the mean entropy values of NSCLC are greater than SCLC, which shows that NSCLC is complex than SCLC extracted using morphological, texture and EFDs features. By employing MSE, the mean value by extracting morphological features, was obtained as NSCLC (0.405), SCLC (0.3397); texture feature as NSCLC (1.7964), SCLC (1.572); EFDs features as NSCLC (2.0266), SCLC (1.846). Likewise, by employing MPE, the mean value by extracting morphological features was obtained as NSCLC (1.373), SCLC (1.386); texture features as NSCLC (2.151), SCLC (2.18); EFDs features as NSCLC (2.218), SCLC (2.112). By employing MSE with KD tree algorithm, the mean value by extracting morphological feature was obtained as NSCLE (0.275), SCLC (0.218), MFE variance as NSCLC (0.164), SCLC (0.003); MFE standard deviation as NSCLC (0.238), SCLC (0.014); RCMFE with mean as NSCLC (0.082), SCLC (0.0297); RCMFE with variance as NSCLC (0.155), SCLC (0.004); RCMFE with standard deviation as NSCLC (0.199), SCLC (0.013). The values for other complexity measures are reflected in the Table 3 and Figure 4.

IV. DISCUSSION AND CONCLUSION

In the past, researchers applied different complexity measures to quantify the dynamics of highly complex and nonlinear dynamical measures by applying Multiscale sample entropy (MSE), MPE, symbolic entropy and refined Fuzzy entropy measures, time-frequency representation measures for detecting epileptic seizures, arrhythmia, heart rate failure, gait dynamics etc. [39], [40], [45]-[48], [56], [87]. The entropy-based complexity measures have been used in diverse fields to quantify the dynamics of highly nonlinear physiological and neurophysiological signals and systems. Single entropy-based measures have some limitations which are alleviated by Costa and Goldberger by introducing new approach as Multiscale sample entropy (MSE) at multiple temporal scales. Moreover, recently, researchers [84] introduced variants of MSE based on variance MSE σ 2. Moreover, Hussain recently employed [39] MSE with KD tree algorithmic approach which is more efficient than traditional MSE due to its robustness in time and space complexity and outperformance. Moreover, in short biological signals, the use of MSE produce undefined and inaccurate results [69], [88]. This problem was addressed by employing refined composite $MSE\mu$ (RCMSE μ) using the average sample entropy values of several coarse-grained signals in each scale factor [69]. The RCMSE μ produced better results than MSE μ , however their exist a problem of undefined values for short signals [69].

This problem was addressed by proposing a composite multiscale fuzzy entropy (RCMFE) based on μ and σ with an aim to provide more accurate and stable results than the traditional entropy measures. RCMFE μ and RCMFE σ were applied to distinguish the AD from control subjects and provides accuracy of 72.81% and 78.22% respectively. Most recently, Hussain extracted Hybrid features using Refined Fuzzy entropy to detect the arrhythmia. The results revealed that Refined Fuzzy outer performed than traditional entropy measures. A highest detection accuracy with sensitivity (100%), specificity (100%) and accuracy (100%) was obtained by extracting refined fuzzy and composite multiscale entropies with mean, variance and standard deviation.

Lung carcinoma is one of the most lethal of cancers worldwide [89]. Positron emission tomography (PET) data has greater sensitivity and specificity in the staging of lung cancer than computed tomography (CT) or magnetic resonance imaging (MRI). By using k- nearest neighbor and support vector machines (SVM) classifiers. Wavelet features with SVM classifier gave a consistent accuracy of 97% with an average sensitivity and specificity of 81% and 99% respectively. Automatic lung nodule detection scheme in [90] is presented in Multi-Slice Computed Tomography (MSCT) scans using SVM. An automatic CAD system is developed for early detection of lung nodule by analyzing lung CT images which achieves 80% result accuracy [91].

Based on the feature extraction approach, researchers employed machine learning techniques to improve the detection performance. This study is aimed to quantify the complex dynamics of lung cancer types by extracting different features based on structure, spatial arrangement and elliptic shapes. Similarly, in quantifying the dynamics of physiological systems including heart rate variability, electroencephalographic (EEG) signals etc., researchers extracted features based on entropy, fuzzy entropy and other nonlinear measures. Researchers [92] extracted Fuzzy entropy as feature in detecting Coronary Artery Disease (CAD) which are originally proposed by [93] to quantify the dynamics of Heart rate variability signals. It is used in many applications such as epilepsy detection [94], characterizing electromyogram [93] and to distinguish focal and non-focal EEG signals [95]. In past few decades, the nonlinear dynamics of physiological signals were computed using various complexity-based measures from information theoretic approaches. Single entropy measures have limitations for shorter data length. To cope up with this problem, Costa et al. proposed multiscale sample entropy [74], [82], [83]. Recently, researchers employed different complexity-based measures to quantify the dynamics of physiological systems [39], [45], [48], [96]-[98], time-frequency representation methods [46]. Based on the diverse nature of physiological signals, [47] most recently

proposed multimodal features extracting strategy based on time domain, frequency domain, statistical, entropy based using KD-tree algorithmic approach and wavelet based features to detect the epileptic seizure with improved detection performance i.e. accuracy (99.50%), specificity (100%), sensitivity (99%), and area under the receiver operating curve i.e. AUC (0.9950) using K-nearest Neighboring approach which outperformed than the studies of [99] using similar approach, however varying feature selection methods. MSE requires computational complexity of order O (N^2) , to cope up this problem, [77] developed MSE with K-d tree algorithmic approach, which is used by [39] and in this study as well require O (N) computational time instead of MSE. Moreover, we have extracted refined Multiscale Fuzzy entropy and refined Multiscale sample entropy features with mean, standard deviation and variance namely (MSE mu, MSE std, MSE var., MFE mu, MFE std, MFE var., RCMSE mu, RCMSE std, RCMSE var.) by taking advantage over recently developed by [68], [100] instead of traditional Fuzzy Entropy features as employed by [92].

The MSE with KD tree algorithmic approach outperformed to distinguished NSCLC from SCLC based on extracted morphological features i.e. MSE with KD tree give P-value (4.43E-11) & MSE with mean give P-value (5.21E-11). Moreover, from extracted texture features, MSE with KD tree provides P-value (6.21E-16) & MSE give P-value (5.48E-7). Similarly, MFE with mean, variance and SD outperformed than traditional MSE with mean and KD algorithmic approaches with extracted morphological and texture features i.e. MFE with mean give significant results of P-value (3.01E-14, 9.81E-34) from extracted morphological and texture features respectively.

By extracting texture features from Lung cancer images, the order of separation was obtained in the following order, the MFE with SD p-value (1.95E-50) followed by MSE with variance P-value (3.25E-36), MFE & RCMFE with mean P-value (9.81E-34), RCMFE with SD P-value (1.67E-30), RCMFE with variance P-value (6.90E-28) at the selected scales where optimal results were obtained. Moreover, by extracting morphological features the highest detection separation was obtained using MFE & RCMFE with mean P-value (3.01E-14) followed by RCMFE with variance Pvalue (1.99E-12), MFE with variance P-value 2.55E-12), MSE with KD tree P-value (4.43E-11), MSE with mean P-value (5.21E-11), MFE with SD provide P-value (1.16E-10). Likewise by extracting EFDs features, the highest separation was obtained using MFE with variance P-value (1.04E-13), followed by MFE with SD P-value (1.82E-12), MPE P-value (3.78E-12), MFE with mean P-value (2.46E-09), MSE with mean P-value (4.08E-7), MSE with KD tree P-value (2.06E-60 and RCMFE P-value (3.89E-5).

The physiological system is comprised of different subsystems being controlled by the regularity mechanism of that system [83], [101]–[103]. If all the subsystems are properly functional and working, the control mechanism of that system will be appropriate and system is healthy. The healthy system evolve with time and their adaptive capability is higher which result in higher complexity. The alternative is the structural components and / or decreased functional capability of the subsystem resulting in dysfunction of the regularity mechanism of the overall systems thereby decrease in complexity. For example, in the human inner ear, the loss of high frequency sound may be caused by alteration in sound receptors, blood supply, neurons, or in the structural changes of the basilar membrane in the inner ear [104].

To determine the complexity of a system, a number of independent variables are required to predict or produce the output of the system. For example, in the skeletal muscle the fiber type expression is dependent on the hormonal, genetic, neuronal, cardiovascular and activity related influences that affect the fast or slow myosin isoform expression in the muscle [105], [106]. The structural components loss is analogous to losing a component variable. To understand the structural component loss, consider an example of dynamics changes due to the loss of dopaminergic cells in the substantia nigra compacta of the Basel ganglia occurring with age and Parkinson's disease. About 80% if the dopaminergic cells in the Parkinson's disease die before most of the behavioral symptoms of Parkinson's disease are observed [107]. This reduce the outflow from internal globus pallidus of the Basel ganglia due to reduction in the dopamine cells and is related to the loss of complexity observed in the tremor output of individuals with Parkinson's disease [108], [109].

There are several examples of reduction of structural components with aging disease including collagen fibers per unit of surface area in skin tissue [110], estrogen hormone activity in females [111], sinus node cells in the heart [112], the number of alveoli of the lungs [113], [114], physical brain damage or even death may happen due to the frequently occurrence of seizures [44], [45], chronic alcohol drinking cause alcohol-related brain damage (ARBD) including brain structure change [39]. The coupling functions between the structural components can influence the dynamics in a system due to the synchronization between the motor units [115], [116]. The motor unit include muscle fibers, nerve and neuromuscular junction where muscle and never fibers communication [117], [118]. The motor unit synchrony changes would represent the altered coupling between the structural components of the nervous systems.

In this study, we extracted the morphological, texture and EFDs features by considering different aspects such as structure and geometry of cancerous images, spatial arrangement of cancer images intensities and ellipse-based characteristics. The researchers in the past extracted different features extracting strategies and classify different machine learning classification measures based on features extracting approaches. However, we aim in this study to quantify the further dynamics of different features extracting strategies by computing the nonlinear dynamics present in the cancer imaging datasets. We applied multiscale sample entropy (MSE) with mean and K-D tree algorithmic approach, Multiscale permutation entropy (MPE), multiscale

TABLE 4. Morphological features.

Morphological Features	Mathematical Equations	Descriptions		
Area (A)	Total amount of Pixel of image	The total Number of pixels in the		
		image		
Perimeter (P)	The amount of Pixel at the boundary	The total amount of pixel at the		
	of the image	boundary of an image which		
		differentiate the regular image from		
		irregular image		
Maximum Radius (MAX_R)	The maximum distance between	To calculate maximum distance		
	center and boundary of an image.	between center of an image to the		
	MAX(DISTANCE(C(x,y), DOLDADX(x,y)))	boundary of an image		
Minimum De line (MDL D)	BOUNDARY(x,y)))	To coloring in the second second		
Minimum Radius (MIIN_R)	I ne minimum distance between	hot was a set of an image to the		
	center and boundary of an image. MIN(DISTANCE($C(x, y)$)	between center of an image to the		
	$\frac{\text{MIN}(\text{DISTANCE}(C(X,Y), Y))}{\text{POLINDARY}(Y,Y)}$	boundary of an image. where x and y		
Euler Number (EUL NO)	No of offected region of an image	It is the difference between the		
Euler Number (EOL_NO)	No of uneffected region of an image	effected region of an image and		
	No of unchected region of an image	unaffected region of an image		
		unarrected region of an image		
Eccentricity (ECT)		It is used for the longthening of an		
Eccentricity (EC1)	$\left 1-\left(\frac{MIN_R}{MIN_R}\right)^2\right $	image		
Equivalianter (EOD)	V (MAX_R)	It is used to calculate diameter of a		
Equivalameter (EQD)	Area	airele which has same area as an		
	$4 * - \pi$	image		
Elongotedness (EN)	(Area)	Flogatondnoss of an image is ratio of		
Elongatedness (EIN)	$\left(\frac{A}{(2-MAY,D)^2}\right)$	length of an image to its thickness		
	$(2 * MAX_R)^2$	square		
Entropy (ENTPY)	$\sum (1 + i)^2$	It is a statistical measure of		
	$\sum (p * log_2(p))$	randomness which is used to		
		characterize the texture of the image.		
Circularity1 (C 1)		It is used to show how an image is		
	Area	resemble as circle		
	$\sqrt{\pi * MAX_R^2}$			
Circularity1 (C 2)		It is used to show how an image is		
· · · · · ·	<u>MIN_R</u>	resemble as ellipse		
	$\sqrt{MAX_R}$			
Compactness (CN)	$(2 * \sqrt{Area * \pi})$	It is used to calculate the degree of		
	$\left(\frac{-\sqrt{1100}}{Porimeter}\right)$	deviation of an image from a Perfect		
	(rennieter)	Circle		
Dispersion (DP)	(MAX_R)	It is used to measure the irregularity		
	(<u>Area</u>)	of an image		
		_		
Standard Deviation of Image		It is used to measure the average		
(SD)	$1 \sum_{n=1}^{n}$	contrast of an image		
	$\left \frac{1}{n}\sum_{i}(x_{i}-\bar{x})^{2}\right $	contrast of an image		
	$\sqrt{\frac{n}{i=1}}$			
Shape Index (SI)	(Perimeter)	It is relates to curved states of an		
	$\left(\frac{1}{2 * MAX R}\right)$	image		

fuzzy entropy (MFE) and refined composite multiscale fuzzy entropy (RCMFE) based on mean, standard deviation and variance to quantify the dynamics at multiple temporal scales. As these nonlinear dynamical measures have been successfully used in many applications to quantify the dynamics of heart rate variability, arrhythmia, epilepsy, gait dynamics,

TABLE 5. Texture features.

S#	Texture Features	Formulas	Description
1	Contrast	$\sum_{x,y=0}^{N-1} P_{x,y} (x-y)^2$	It is used to calculate the intensity contrast b/w a pixel and its neighbor one of the whole images
2	Correlation	$\sum_{x,y=0}^{N-1} P_{x,y} \left[\frac{(x - \mu_x)(y - \mu_y)}{\sqrt{(\sigma_x^2)(\sigma_y^2)}} \right]$	It is used to calculate the degree of correlation b/w pixel and its neighbor one of the whole images
3	Dissimilarity	$\sum_{x,y=0}^{N-1} P_{x,y} x-y $	To calculate the difference in images
4	Energy	$\sum_{x,y=0}^{N-1} P_{x,y}^2$	It is used to calculate the uniformity of an image
5	Entropy	$\sum_{x,y=0}^{N-1} P_{x,y} \left(-ln P_{x,y}\right)$	It is used to calculate the information encoded in the image
6	Homogeneity	$\sum_{x,y=0}^{N-1} \frac{P_{x,y}}{1+(x-y)^2}$	It is used to calculate the spatial closeness of the distribution of elements in G to the diagonal.
7	Mean	$ \mu_{x} = \sum_{x,y=0}^{N-1} x (P_{x,y}) \& \qquad \mu_{y} = \sum_{x,y=0}^{N-1} y (P_{x,y}) $	It is used to calculate the sum of all possible images and P is the probability mass function.
8	Variance	$\sigma_x^2 = \sum_{x,y=0}^{N-1} P_{x,y} (x - \mu_x)^2 \& \sigma_y^2 = \sum_{x,y=0}^{N-1} P_{x,y} (y - \mu_y)^2$	It is used to calculate how far a set of (random) numbers are spread out from their mean
9	Standard Deviation	$\sigma_x = \sqrt{\sigma_x^2} \qquad \& \qquad \sigma_y = \sqrt{\sigma_y^2}$	It is used to calculate to quantify the amount of variation or dispersion_of a set of data values
10	Skewness	$\frac{1}{N \times N} \sum_{i=0}^{N} \sum_{j=0}^{N} \left[\frac{p(i,j) - \mu}{\sigma} \right]^{3}$	Skewness is used to obtain the degree of asymmetry of any pixel around its mean.
11	Kurtosis	$\frac{1}{N \times N} \sum_{i=0}^{N} \sum_{j=0}^{N} \left[\frac{p(i,j) - \mu}{\sigma} \right]^4$	This formula can compute the flatness or peakness of a distribution.
12	RMS	$\sqrt{\frac{p(i,j)^2}{N \times N}}$	Root mean square (RMS) is used to calculate the error between known and predicted value.

human activity dynamics, and brain dynamics. The small cell lung cancer (SCLC) spread more faster to the other organs than non small cell lung cancer (NSCLC) type. Patients sometime may not early experience the symptoms associated with lung cancer until cancer reached at its advanced stage. Based on the recent findings, the NSCLC contain more complex dynamics, spread slowly than the SCLC type which spread very rapidly. Based on the findings of the recent study by applying multiscale entropy measures to quantify the dynamics for early diagnosis and prognosis of NSCLC can help the radiologists, oncologists and medical specialists to further promulgation towards advanced stages. The results further reveal that NSCLC based on the robust complexity measures exhibit complex dynamics at multiple temporal scales which can further studied for more comprehensive analysis. The findings also consistent with the previous studies. Recently, Hussain computed the complexity of epileptic subjects (ictal intervals- with seizure) and epileptic subjects (interictal interval – without seizures) and obtained that interictal interval subjects contain more complex dynamics than the ictal interval subjects with seizures. The interictal interval can be focal and non-focal signals effecting only part of body, which may be converted to generalized seizures by effecting whole body. Lung cancer is categorized in two types i.e. NSCLC type which is present in 85 % and SCLC type in 15%, which are classified [43] based on different features extraction approaches as proposed by [18], [20] and employing machine learning techniques. However, NSCLC having complex dynamics can be transformed to SCLC [2] if not properly and timely treated. This study reveals that complexity measure can help us to further quantify the dynamics of these two cancer types. The findings of the recent study shows that refined fuzzy entropy [68], [100] instead of traditional Fuzzy Entropy features as employed by [92] exhibit higher separation to distinguish the NSCLC and SCLC that traditional entropy measures.

Lung cancer is the most severe cancers in the world with the minimum survival ratio after the analysis [119]. It is the most common cause of life internationally. The incidence of lung cancers has multiplied unexpectedly and come to be the most common cancer in maximum countries. The research is done in order to separate SCLC groups from that of NSCLC groups using the entropy-based method with various features extraction techniques i.e. Texture Feature, Morphological feature, and Elliptic Fourier Descriptors (EFDs. Using these entropy measures, we calculated Mean, Standard deviation and P-value at different scales against each group (NSCLC and SCLC) on the basis of extracted features values. The minimum P-value against the groups shows the most significant results and exhibit the good separation between the groups. The greater mean value shows the higher complexity for the class. If we compare all the results extracted using Texture feature between two groups (NSCLC AND SCLC), then we clearly say that the more significant value is obtained using MFE with SD having minimum P-value (1.95E-50). By extracting morphological features, the highest separation was obtained using MFE with mean having minimum P-value (3.01E-14). The results indicated that entropy measures are a very helpful methods to measure the dynamics of lung cancer for early detection and prognosis.

LIMITATIONS AND FUTURE RECOMMENDATIONS

In the present study, we distinguish the NSCLC from SCLC only based on available lung cancer imaging database by employing various non-linear dynamical measures. In future, we will compare the dynamics of both types of cancers with healthy lung cells.

APPENDIX//ANNEX-A

See table 4 and 5.

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